

**ODA3 INSTITUTE**

**QUICK START GUIDE**

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# **PAI-SF™ Quick Start Guide**

First 30 Days of Practitioner Onboarding

ODA3-2026-07-QSG-PAISF-008 | Public-Facing — Publication Support Document

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## Document Control

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|------------------------------------|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| <b>Doc ID</b>                      | ODA3-2026-07-QSG-PAISF-008                                                                                                                                                                      |
| <b>Doc Type</b>                    | Quick Start Guide                                                                                                                                                                               |
| <b>Framework Tag</b>               | PAI-SF™ v1.0                                                                                                                                                                                    |
| <b>Governing Licence</b>           | GAISSF Ecosystem Licence (GEL v1.0)                                                                                                                                                             |
| <b>Access Classification</b>       | Open / Public — onboarding guidance; no Controlled-asset material (assessment methodology, scoring rubric, scenario bank, assessor decision logic remain Controlled and are not disclosed here) |
| <b>Publication State</b>           | Publication Candidate — pending formal publish action                                                                                                                                           |
| <b>Publish Date / Review Cycle</b> | 01 August 2026 (content finalized); publication date to be confirmed                                                                                                                            |
| <b>Classification</b>              | Public-Facing — Publication Support Document                                                                                                                                                    |

# PAI-SF™ Quick Start Guide

## First 30 Days of Practitioner Onboarding

## Purpose

This guide helps teams begin using PAI-SF without treating the full framework, control catalogue, or assessment methodology as a prerequisite. It is an onboarding document, not a certification decision, audit result, or replacement for functional safety certification.

This guide assumes familiarity with **Kinetic Zero Trust** — PAI-SF's core assurance principle, that AI-generated physical actions must be validated against independent safety boundaries rather than trusted on the model's own confidence or authorization alone. See the Framework Standard (ODA3-2026-07-NOR-PAISF-005) for the full definition before beginning system scoping.

## 1. Use This Guide When

- A system can sense, decide, and cause physical action through actuators, robots, drones, vehicles, industrial equipment, medical robotics, or edge cyber-physical infrastructure.
- Security work must address the chain from perception to model decision, autonomy boundary, kinetic command, physical effect, monitoring, intervention, and recovery.
- A team needs an initial scoping, evidence, or readiness path before a formal assessment is planned.

## 2. First 30-Day Start Path

- 1. Confirm the system boundary.** Define the physical AI system, operating environment, connected assets, autonomy level, actuator classes, human operators, and update channels.
- 2. Classify physical consequence paths.** List how software, model output, sensor error, or compromised identity could create physical motion, interruption, collision, unsafe exposure, or recovery difficulty.

**3. Map the 12 domains.** Mark each domain as applicable, partially applicable, not applicable, or pending evidence. Do not exclude a domain merely because ownership sits with a vendor or safety team.

**4. Collect starter evidence.** Gather existing architecture diagrams, sensor and actuator inventories, logs, test reports, safety case references, update records, and incident procedures.

**5. Identify control gaps.** Compare the collected evidence against the Framework Standard and Control Catalogue. Separate missing evidence from missing implementation.

**6. Set the next decision.** Decide whether the next step is remediation planning, partner-led implementation support, a controlled assessment-readiness review, or sector-specific guidance.

### 3. Minimum Scoping Questions

- What physical actions can the system cause directly or indirectly?
- Which sensors and perception models influence those actions?
- Where are autonomy boundaries defined, enforced, logged, and changed?
- What independent stop, override, or safe-state mechanisms exist?
- What runtime telemetry would prove what happened during an abnormal event?
- What update, supply-chain, and third-party components can affect perception, autonomy, or actuation?
- What evidence exists for hardware-in-the-loop, adversarial, degraded-mode, and sim-to-real testing?

### 4. Domain Quick Map

Use this table for initial scoping only. The Control Catalogue remains the authoritative control-level reference.

| No. | Domain                                | Control Family | What to Check First                                                                    |
|-----|---------------------------------------|----------------|----------------------------------------------------------------------------------------|
| 1   | Sensor and Perception Integrity       | SEN            | Sensor input trust, calibration, spoofing resistance, and perception assurance.        |
| 2   | Actuator and Kinetic Command Safety   | ACT            | Command validation, rate limits, replay resistance, and actuator divergence detection. |
| 3   | Edge Hardware and Model Attestation   | ATT            | Device, model, boot, and attestation-key trust at the physical edge.                   |
| 4   | Autonomy Boundaries                   | AUT            | Authorized operating envelope, autonomy level, and ODD change control.                 |
| 5   | Safe-State and Degraded-Mode Behavior | SAF / DEG      | Safe-state triggers, fallback behavior, and graceful degradation evidence.             |
| 6   | Human Override and Intervention       | HOV            | Independent override, emergency stop, operator readiness, and reset integrity.         |

| No. | Domain                                  | Control Family | What to Check First                                                                          |
|-----|-----------------------------------------|----------------|----------------------------------------------------------------------------------------------|
| 7   | Runtime Monitoring and Telemetry        | TEL            | Independent telemetry, coverage, synchronization, retention, and anomaly context.            |
| 8   | Incident Response and Physical Recovery | IRP            | Physical containment, evidence preservation, recovery, and return-to-service checks.         |
| 9   | Supply Chain and Update Assurance       | SUP            | Component provenance, update controls, staged rollout, and supplier assurance.               |
| 10  | Simulation, Testing, and Validation     | TST            | Hardware-in-the-loop, adversarial tests, scenario libraries, and sim-to-real evidence.       |
| 11  | Functional Safety Interface             | FSI            | Security-safety interface evidence without replacing formal functional safety certification. |
| 12  | Physical Operating Environment          | ENV            | Operating context, site conditions, physical constraints, and environmental monitoring.      |

## 5. Evidence Starter Pack

The following evidence categories are enough to begin a first readiness review, covering all 12 domains. They are not a complete assessment record.

| Control Family | Domain | Evidence Area                        | Starter Material to Collect                                                                     |
|----------------|--------|--------------------------------------|-------------------------------------------------------------------------------------------------|
| SEN            | D1     | Sensor / perception evidence         | Sensor inventory, calibration status, spoofing/tamper assumptions, perception failure examples. |
| ACT            | D2     | Kinetic command evidence             | Command validation rules, rate limits, actuator logs, replay-prevention evidence.               |
| ATT            | D3     | Edge hardware / attestation evidence | Secure boot records, hardware bill of materials, attestation key custody documentation.         |
| AUT            | D4     | Autonomy boundary evidence           | Operating-design-domain definition, allowed autonomy levels, boundary-change approvals.         |
| SAF / DEG      | D5     | Safe-state evidence                  | Trigger rules, fallback behavior, degraded-mode                                                 |

| Control Family | Domain | Evidence Area                        | Starter Material to Collect                                                                    |
|----------------|--------|--------------------------------------|------------------------------------------------------------------------------------------------|
|                |        |                                      | procedures, recovery readiness checks.                                                         |
| HOV            | D6     | Human intervention evidence          | Emergency stop design, operator authority, intervention drills, reset controls.                |
| TEL            | D7     | Runtime telemetry evidence           | Independent telemetry sources, coverage map, time sync, retention, anomaly records.            |
| IRP            | D8     | Incident/recovery evidence           | Containment playbooks, evidence-preservation procedures, return-to-service test records.       |
| SUP            | D9     | Supply-chain and update evidence     | Component provenance, firmware/model version records, staged rollout evidence.                 |
| TST            | D10    | Testing evidence                     | Scenario library, hardware-in-the-loop tests, adversarial tests, sim-to-real gap records.      |
| FSI            | D11    | Functional safety interface evidence | Hazard analysis cross-reference, safety-case gap register, exception escalation records.       |
| ENV            | D12    | Operating environment evidence       | Environment specification, environmental monitoring logs, human proximity zone design records. |

## 6. Initial Readiness Levels

- **Level 0 — Unscoped:** the system boundary, physical consequence paths, or domain applicability are not yet defined.
- **Level 1 — Identified:** applicable domains are known and basic ownership is assigned, but evidence is incomplete.
- **Level 2 — Evidence-started:** architecture, logs, test records, and operating procedures exist for major consequence paths.
- **Level 3 — Review-ready:** evidence is mapped to controls, gaps are separated from exclusions, and responsible owners are named.
- **Level 4 — Assessment-ready:** evidence is stable, repeatable, retained, and ready for controlled methodology review.

## 7. What Not to Claim From This Guide

**Notably Absent:** This Quick Start Guide does not certify a system, score control maturity, validate functional safety compliance, approve a product for deployment, or authorize commercial delivery of

PAI-SF services outside ODA3's licensing and partner ecosystem. It also does not provide the controlled assessment methodology, scoring rubric, scenario bank, or assessor decision logic.

## 8. Relationship to Other PAI-SF Documents

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- **Framework Standard:** normative anchor for scope, domain architecture, principles, boundaries, and control index.
- **Control Catalogue:** authoritative 41-control reference and the next place to look after initial scoping.
- **Assessment Methodology and Scoring Rubric:** Controlled assets for structured assessment and maturity decisions.
- **Sector Guides:** deployment-context guidance for robotics, autonomous vehicles, medical robotics, and related physical AI systems.

## 9. Recommended Next Actions

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- Create a one-page system boundary note before mapping controls.
- Build the first evidence folder around all 12 domains, not only the most familiar ones.
- Use the Control Catalogue to identify which controls require evidence versus which require implementation change.
- Do not publish conformance or certification claims until the controlled assessment and licensing pathway is resolved.